WHAT IS CLAIMED IS:

1	1.	A probe microscope comprising:
2		a probe;
3		a scanner for generating relative motion between said probe and a sample;
4		a manual input device having a substantially unlimited range of
5		mechanical motion to control a separation between the sample and said
6	probe, said m	nanual input device having a substantially unlimited range of mechanical
7	motion;	
8		a detector that generates a probe motion signal related to movement of
9	said probe;	
10		an alerting device responsive to said signal to provide substantially real-
11	time feedbac	k to an operator, the feedback being indicative of interaction between the
12	sample and s	aid probe.
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1	2.	The probe microscope of Claim 1, wherein said alerting device is a
2	mechanical resistance device coupled to said manual input device.	
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1	3.	The probe microscope of Claim 2, wherein said manual input device is a
2	rotatable kno	b.
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1	4.	The probe microscope of Claim 3, wherein said resistance device is a
2	passive resist	ance device that changes an amount of torque necessary to turn the knob.
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1	5.	The probe microscope of Claim 4, wherein said passive resistance device
2	is a brake.	
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1	6.	The probe microscope of Claim 4, wherein the amount of torque is related
2	to a magnitud	le of the interaction.
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1	7.	The probe microscope of claim 2, wherein said resistance device is an
2	active resistar	nce device.
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1	8.	The probe microscope of Claim 7, wherein said active resistance device
2	actively mov	es said manual ingut device.
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1	9.	The probe microscope of Claim 2, wherein the feedback produced by said
2	resistance de	vice is variable.
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1	10.	The probe microscope of Claim 9, wherein the probe motion signal is
2	indicative of	a tip-sample interaction, and wherein the variable resistance is related to the
3	interaction.	
4		
1	11.	The probe microscope of Claim 1, wherein the feedback produces an
2	audible outpu	at, wherein the audible output is related to a magnitude of the interaction.
3		
1	12.	The probe microscope of Claim 11, wherein the audible output is one of
2	pitch and vol	- W
3	•	
1	13.	The probe microscope of Claim 1, further comprising
2		a displacement sensor that measures the relative motion between said
3	probe and the	e sample and generates a corresponding position signal; and
4	P	a closed-loop feedback controller that generates a drive signal in response
5	to the positio	()
6	to the positio	
U		ll .

The probe microscope of Claim 3, wherein said knob has a range of 14. motion greater than 180°.

The probe microscope of Claim 1 wherein the feedback is one of 15. substantially proportional, exponential and logarithmic with respect to the interaction.

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1	16.	A method of making a force curve measurement on a sample, the method
2	comprising:	
3		manually controlling a separation between a probe and the sample;
4		measuring the separation;
5		detecting a force on the probe in response to said generating step;
6		providing an alert based on the force; and
7		wherein said controlling step includes using a rotatable knob.
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1	17.	The method of Claim 16, wherein said providing step includes using a
2	brake to conti	rol a torque required to rotate the knob.
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1	18.	The method of Claim 17, wherein the torque is proportional to the force.
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1	19.	The method of Claim 16, wherein the knob has a range of motion greater
2	than 180°.	
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1	20.	The method of Claim 16, further comprising the step of repeating said
2	controlling st	ep in response to at least of one said measuring and detecting steps.
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1	21.	The method of Claim 16, wherein the alert is an audio alert.
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1	22.	A probe microscope including a probe that interacts with a sample, the
2	microscope c	1
3		a manual rotary input knob that modulates a separation between the probe
4	and the samp	le, said knob having a range of motion greater than 180°;
5		an alerting device responsive to interaction between the probe and the
6	sample so as	to provide feedback to the operator, the feedback being indicative of a
7	magnitude of	the interaction.
8		
1	23.	The probe microscope of Claim 22, wherein said alerting device is a
2	brake.	\